



A unity feedback control system is characterized by an open loop transfer function. 5 a.

 $G(S) = \frac{10}{s^2 + 2s + 6}$, determine the following, when the system is subjected to a unit step input i) Undamped natural frequency ii) Damping ratio iii) Peak time iv) Settling time v) Peak overshoot. (10 Marks)

b. By applying Routh's criterion discuss the stability of the closed loop system whose characteristic equation is $s^6 + 3s^5 + 4s^4 + 6s^3 + 5s^2 + 3s + 2 = 0$ (10 Marks)

Sketch the complete Root locus for the system having

$$G(s)H(s) = \frac{K}{s(s+3)(s^2+3s+11.25)}$$
 and comment on stability. (20 Marks)

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- Draw the Bode plot for a system having $G(s)H(s) = \frac{100}{s(s+1)(s+2)}$. Find: i) Gain margin 7 iii) Gain cross over frequency iv) Phase cross over frequency and ii) Phase margin comment on stability. (20 Marks)
- Draw the polar plot and ascertain the nature of stability for system with open loop transfer 8 a. function G(s)H(s) = $\frac{1}{(s+1)(s+2)(s+3)}$ (10 Marks)
 - Draw the Nyquist plot for a b. system with open loop transfer function $G(s)H(s) = \frac{1}{s(1+2s)(1+s)}$ and comment on stability. (10 Marks)
- 9 Explain series and feedback compensation with block diagrams. a. (12 Marks) b. Explain controllability and observability with reference to control system. (08 Marks)
- 10 Explain the following terms: a. iv) State space v) State equation. ii) State variable iii) State vector i) State (10 Marks)
 - Discuss lag compensator, sketch the bode plot of a lag compensator. b. (05 Marks)
 - Discuss lead compensator, sketch the bode plot of lead compensator. (05 Marks)

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